# WHAT IS A MULTI-MOMENT MAP?

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September 2010 / Porto

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Joint work with Thomas Bruun Madsen

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Symplectic Geometry Strong Geometry Covariant Moment Maps

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such that  $d\langle \mu, X \rangle = X \,\lrcorner\, \omega$ , for each  $X \in \mathfrak{g}$ .

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The moment map  $\mu \colon \mathcal{O} \to \mathfrak{g}^*$  is just inclusion.

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  - **4** *G* is semi-simple.

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## Strong geometry

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WHAT IS A MULTI-MOMENT MAP? ANDREW SWANN

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$$\alpha: M \to \Omega^1(M, \mathfrak{g})$$

such that  $d\langle \alpha, X \rangle = X \,\lrcorner\, c$ , for each  $X \in \mathfrak{g}$ .

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- Problems include:
  - **1** Target space  $\Omega^1(M, \mathfrak{g})$  depends both on *M* and  $\mathfrak{g}$ .
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# Outline

# **1** BACKGROUND

Symplectic Geometry Strong Geometry Covariant Moment Maps

# 2 MULTI-MOMENT MAPS Commuting vector fields

Lie kernels Existence (2, 3)-trivial Lie algebras

# **3** $G_2$ holonomy

Reduction Conformal geometry

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Linearity in the basic calculation shows that

$$d(p \,\lrcorner\, c) = d(\sum_{i=1}^{r} c(X_i, Y_i, \cdot)) = -(\sum_{i=1}^{r} [X_i, Y_i]) \,\lrcorner\, c = 0.$$

WHAT IS A MULTI-MOMENT MAP?

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- For *G* semi-simple, Λ<sup>2</sup> g ≅ g ⊕ P<sub>g</sub>. In particular, for *G* compact and simple, P<sub>g</sub> is the isotropy representation of the isotropy irreducible space SO(dim g)/G.

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ANDREW SWANN WHAT IS A MULTI-MOMENT MAP?

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is the description of SU(3) as a hypercomplex (HKT) Swann bundle over the quaternionic Kähler  $\mathbb{CP}(2)$ .

## Homogeneous spaces and orbits

WHAT IS A MULTI-MOMENT MAP? ANDREW SWANN

### Homogeneous spaces and orbits

Homogeneous strong manifolds (G/H, c)

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## OUTLINE

### **1** BACKGROUND

Symplectic Geometry Strong Geometry Covariant Moment Maps

### **2** Multi-moment maps

Commuting vector fields Lie kernels Existence (2, 3)-trivial Lie algebras

### **3** $G_2$ HOLONOMY

Reduction Conformal geometry

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- There exist unimodular (2, 3)-trivial Lie groups admitting compact discrete quotients (dim *G* ≥ 5).

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# **3** G<sub>2</sub> HOLONOMY Reduction

Conformal geometry

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$$\omega_0 = U_1 \,\lrcorner\, U_2 \,\lrcorner\, *\phi, \quad \omega_i = U_i \,\lrcorner\, \phi, \quad \ell^2 = \|U_1 \wedge U_2\|^2.$$

# Reduction of $G_2$ structures

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One has

$$\frac{1}{\ell^2}\omega_0^2 = \frac{1}{\|U_i\|^2}\omega_i^2 = 2\operatorname{vol}_M,$$
$$\omega_0 \wedge \omega_i = 0, \quad \omega_1 \wedge \omega_2 = 2\langle U_1, U_2 \rangle \operatorname{vol}_M.$$

# Outline

# **1** BACKGROUND

Symplectic Geometry Strong Geometry Covariant Moment Maps

### **2** Multi-moment maps

Commuting vector fields Lie kernels Existence (2,3)-trivial Lie algebras

### **3** $G_2$ holonomy

Reduction Conformal geometry

Putting  $\Lambda_+ = \operatorname{span}_{\mathbb{R}} \{\omega_0, \omega_1, \omega_2\}$  defines a conformal structure  $\mathcal{C}_{\omega}$  on  $M^4$ .

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# CONFORMAL GEOMETRY

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Suppose  $\omega_j$  are symplectic forms on M defining the same orientation. Let g be a metric in the conformal class  $C_{\omega}$ . Suppose g is positive definite,  $\omega_0 \wedge \omega_i = 0$ , i = 1, 2, and that  $Q = (\langle \omega_i, \omega_j \rangle)_{i,j=1,2}$  is positive definite.

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# Lifting

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 $M^4 \rightarrow T^4 / \{\pm 1\}$  a Kummer surface, with  $\omega_c = \omega_1 + i\omega_2$  complex symplectic and integral.

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More general than Apostolov and Salamon (2004): we do not need a hyperKähler triple  $\omega_i$ . Donaldson (2006) asks whether the underlying compact manifold is always hyperKähler.

# SUMMARY

• Multi-moment maps are defined  $\nu \colon (M, c) \to \mathcal{P}_{\mathfrak{g}}^*$ , where  $\mathcal{P}_{\mathfrak{g}} = \ker([\cdot, \cdot] \colon \Lambda^2 \mathfrak{g} \to \mathfrak{g}).$ 

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- (2,3)-trivial Lie algebras may be classified in small dimensions and described and as certain one-dimensional solvable extensions of nilpotent algebras in general.
- *G*<sub>2</sub> holonomy manifolds with *T*<sup>2</sup>-symmetry correspond via multi-moment map reduction to conformal data on *M*<sup>4</sup> defined by a certain type of triple of symplectic forms.

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